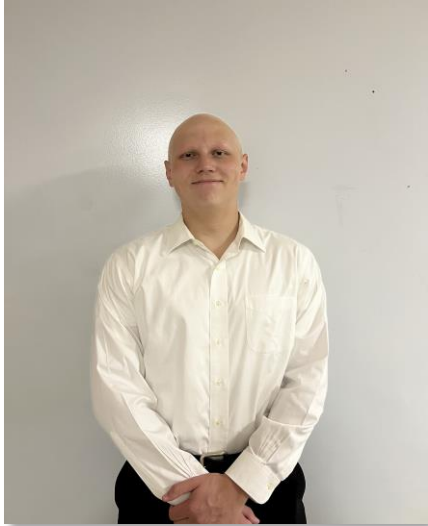


Senior Design Team 302:

Design/Prototype a Multi-Platform
Broadband Communication Payload for a
Search and Rescue Operation

Sponsor – Northrop Grumman

Introductions



Theodore Houck ~
Financial Advisor



Nicholas Crenshaw ~
Lead CPE



Jarrod Love ~
Lead EE



Matthew Brown ~
Team Leader

Sponsor Contact – Lin, Anny
Advisor – Dr. Arora

Outline

- Project Recap
- Preliminary Design
- Preliminary Results
- Where we are now

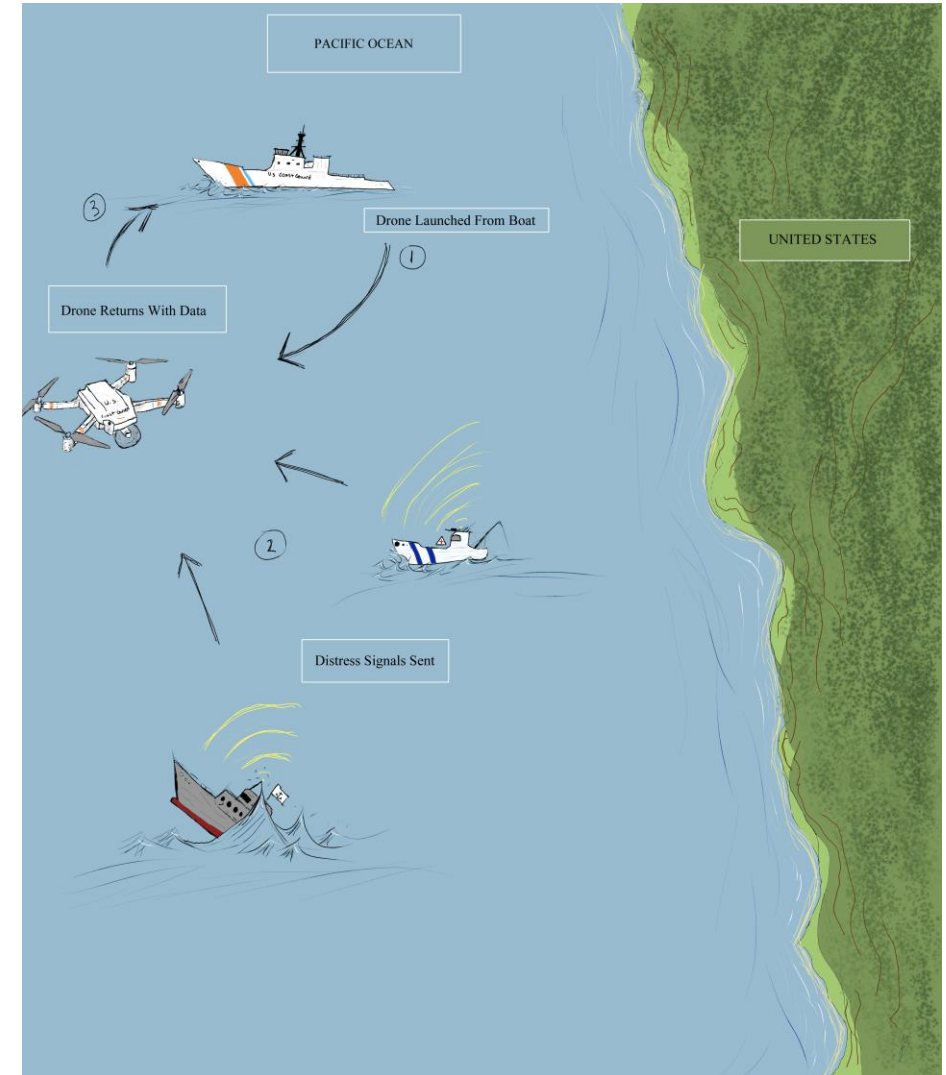


Presenter: Jarrod Love



Background of Project

- A natural disaster has occurred off the coast. Several ships have been severely damaged in such a way that they are unable to return to shore.
- These ships and yachts must be located so that search and rescue (SAR) operations such as emergency helicopters and lifeboats can be deployed to support stranded people and vessels.



Presenter: Jarrod Love

Scope of Project

Key Goals

1. Payload can detect emergency signals found in typical emergency radar beacon signal
2. Once detected a timestamp of the detection and current GPS location will be stored
3. The payload should be able to attach to a drone without majorly hindering the function of the drone

Assumptions

- Team will be given a data sheet/information about the drone
- Detection algorithm needed for payload is provided by sponsor and is feasible



Markets

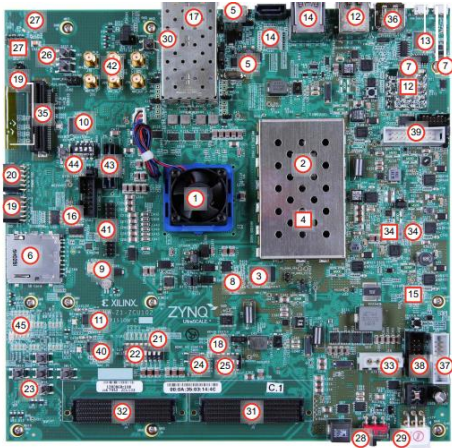
- Primary Market - U.S. Coast Guard
- Secondary Market - Various emergency responders or U.S. Military

Stakeholders

- Northrop Grumman
- United States Coast Guard
- United States Military

Presenter: Jarrod Love

Parts



FPGA

Xilinx Zynq UltraScale+
MPSoC ZCU102



SD CARD

SanDisk 32GB Ultra SDHC UHS-I
Memory Card - 120MB/s



Power Source

BatteryGuy 12V 220 mAh
Alkaline Door Lock Battery



Antenna

VHF stout and long antenna
SMA connector 147-160MHz

Presenter: Nicholas Crenshaw

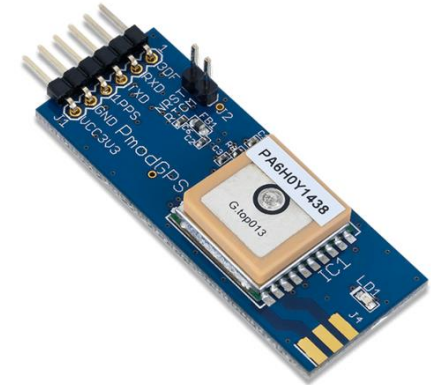
Components



Transceiver
AD-FMCOMMS4-EBZ
Wideband Software Defined
Radio Board

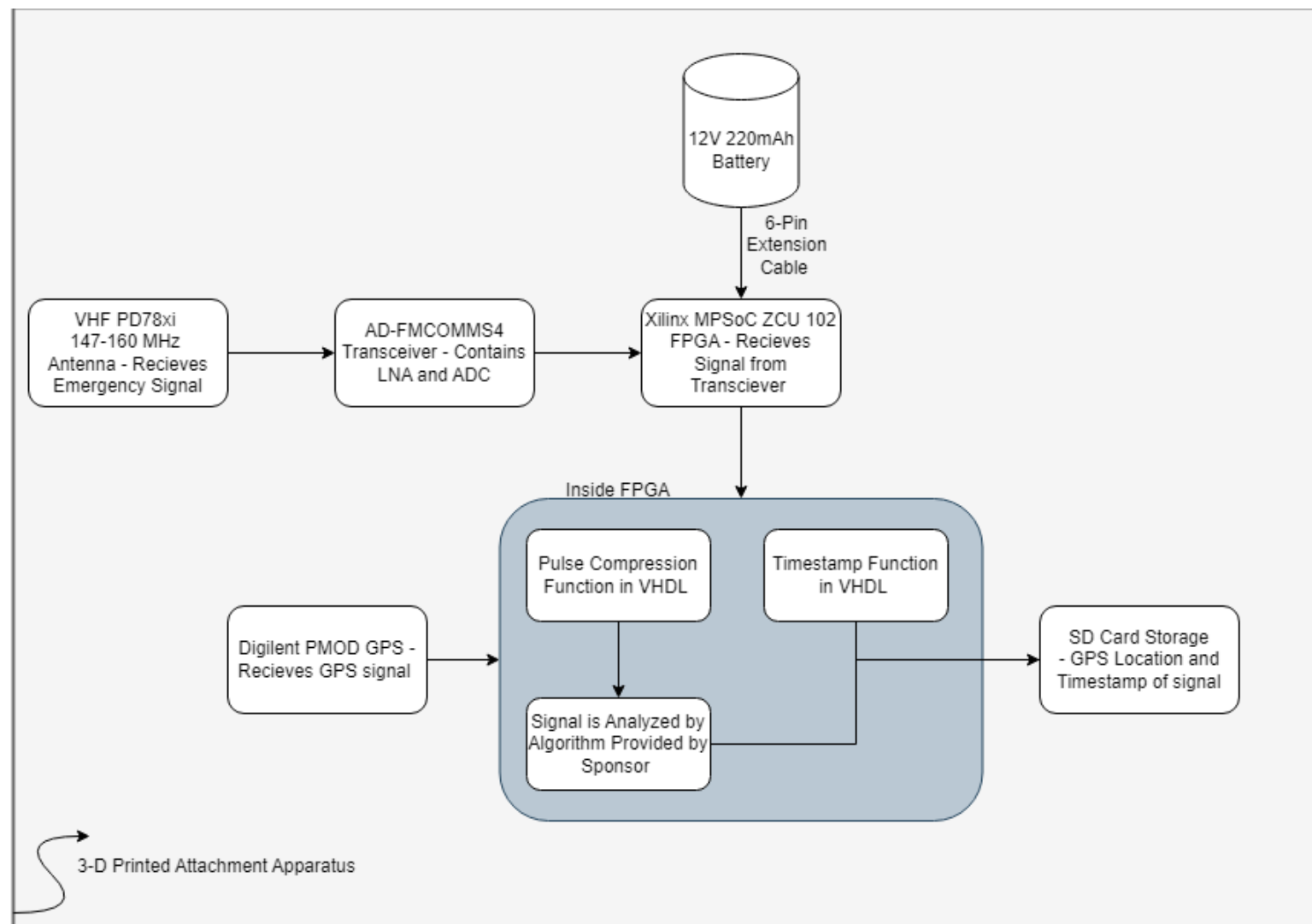


Battery Connectors
Cable Matters 2-Pack 6 Pin
PCIe Extension Cable 10
Inches



PMOD GPS
Digilent GPS Receiver

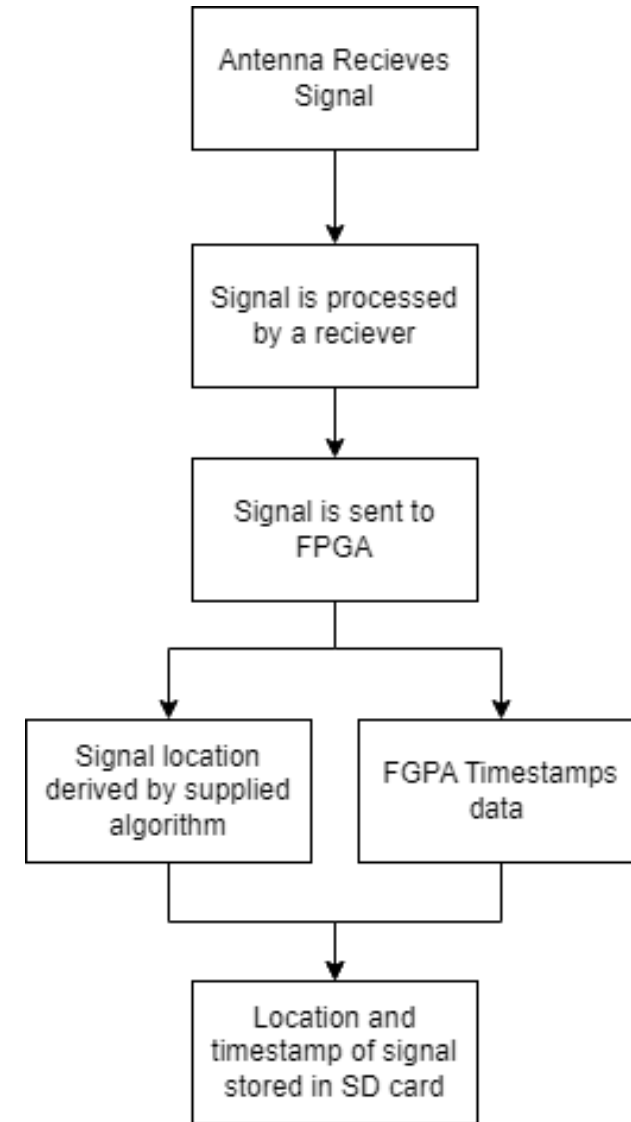
Preliminary Design Block Diagram



Presenter: Nicholas Crenshaw

Planned Solution

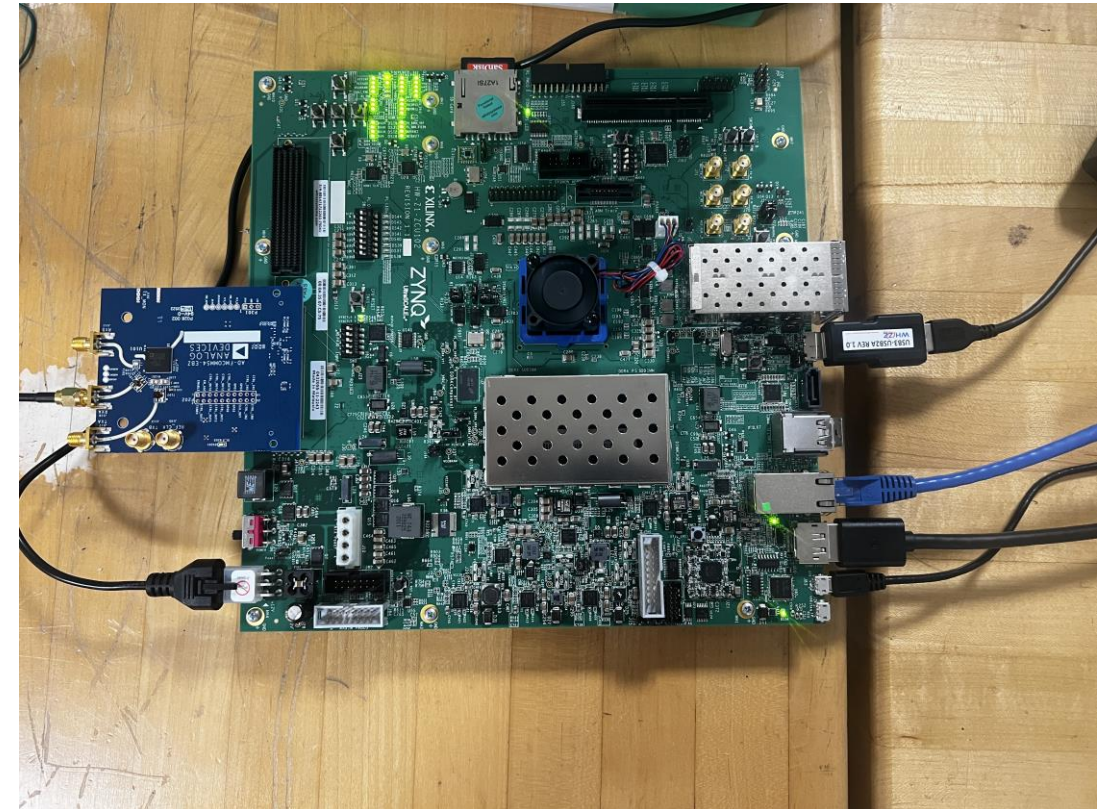
- This diagram follows the path of the signal
- Additional parts of the planned design solution are the following
 - Independent battery source
 - Payload container shall be water resistant



Presenter: Nicholas Crenshaw

Transceiver Module Progress

- Original idea was to plug into FPGA and code to it
- Documentation for the receiver do not say what pins are needed to program/read data to/from transceiver
 - FMC Connection (68 single-ended, 34 differential user-defined pair pins)
- The suggested method from the dealer is to setup up their local Linux environment on the FPGA



Presenter: Matthew Brown

Transceiver Module Progress

- Took approximately 1 month to setup the transceiver and this Linux environment
- Main issues:
 - Did not know how to connect to console UART on FPGA
 - Had no experience with setting up a Linux environment/image
 - Display was not working
 - Peripherals in device tree were setup incorrectly
 - Once environment was setup it was not detecting the transceiver

```
I2C:  ready
DRAM:  4 GiB
EL Level:      EL2
Chip ID:       zu9eg
MMC:  sdhci@ff170000: 0 (SD)
reading uboot.env
In:  serial@ff000000
Out: serial@ff000000
Err: serial@ff000000
Net:  ZYNQ GEM: ff0e0000, phyaddr 15, interface rgmii-id
eth0: ethernet@ff0e0000
## Error: "setup" not defined
Hit any key to stop autoboot:  0
run - run commands in an environment variable

Usage:
run var [...]
    - run the commands in the environment variable(s) 'var'
## Error: "distro_bootcmd" not defined
ZynqMP>
```

Presenter: Matthew Brown

Transceiver Module Progress

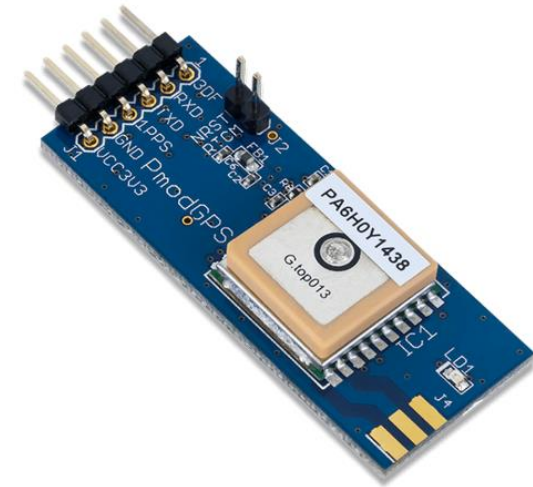
- Total implementation of transceiver ~90%
- Currently able to detect signals coming from the signal generator via a direct SMA cable
- Need to test antennas
- The current FPGA local Linux environment/program setup allows to change numerous settings on FPGA



Presenter: Matthew Brown

PMOD GPS Module Progress

- GPS Module was a recent addition
- Have not started implementing the PMOD GPS
- Focus was getting the transceiver to work the past couple of weeks

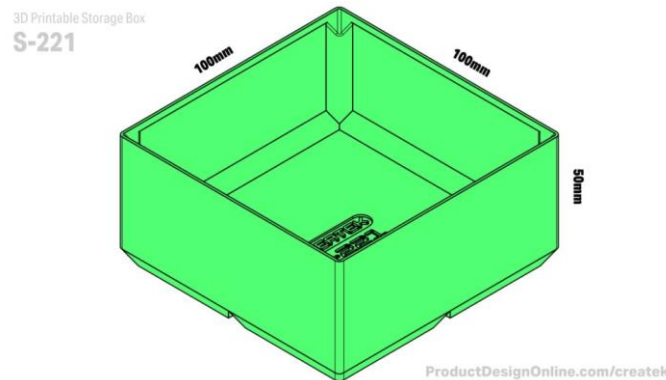


Presenter: Matthew Brown



Housing Progress

- The 3-D printed housing for the design is currently in production
- The design for said housing is completed
- Will be printed using FSU's provided 3D printers

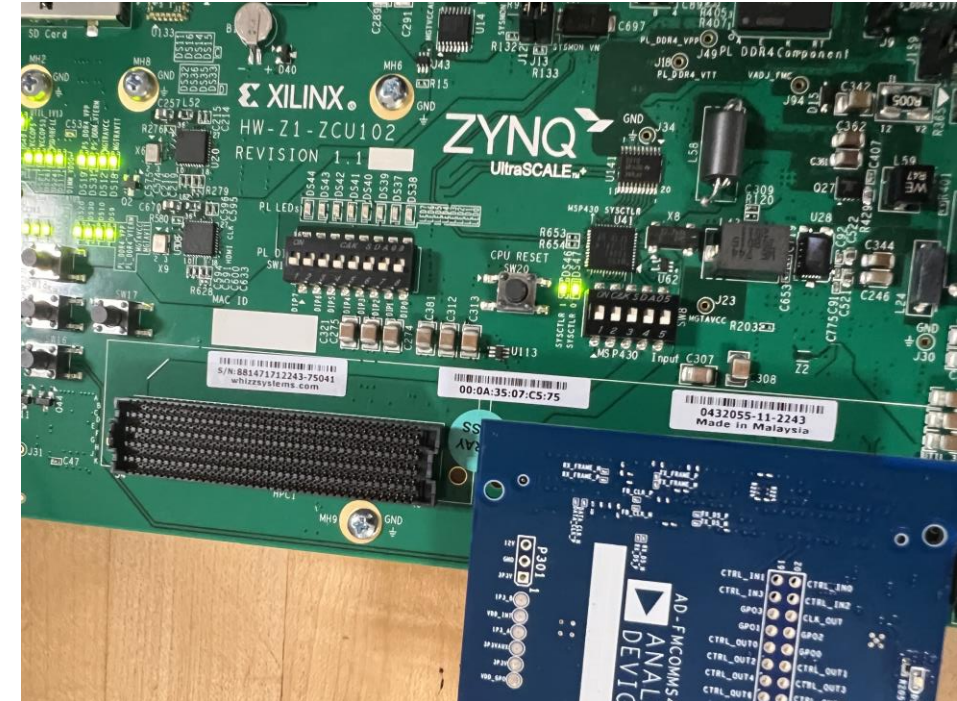


Presenter: Theodore Houck



What's Next

- **Transceiver**
 - Setup grab data from DDR4 memory on FPGA using VHDL
 - Combine this with PMOD GPS time data for timestamping
- Test antennas attached to transceiver and a signal generator
- Test remote power source for FPGA
- Test housing design
- Calculate and test limits of design



Presenter: Theodore Houck

Summary

- The FPGA has been configured for operation with a working GUI interface.
- The transceiver has been configured to operate with the FPGA.
- Signals received by the payload can now be displayed and **viewed**. *However, this has only been achieved by direct connection, and signal detection from the antenna has yet to be established.
- The payload's housing is awaiting 3-D printing.

Presenter: Theodore Houck

Thanks for Listening! Questions?

